

IFPRI BRIEF TEMPLATE

Check One: ⊠Project □Workshop

Review **□**Other

□ Collaboration

Descriptive Title	Contact dynamics of multi-phase colloidal suspensions	
Working Title ¹	Multi-phase colloidal suspensions	
Technical Area ²	Wet Systems	
Date	· · · · · · · · · · · · · · · · · · ·	
Short Description	The wetting and dispersion of gums, biomacromolecules (starches, celluloses), and other fine powders requires and the design of, or is inhibited by, particle-stabilized structures, such as Pickering emulsions, Pickering foams and bijels, requires the characterization and modeling of contact between multiple-phases (solid-liquid-gas). A first-principles understanding of especially the dynamics of these processes remains an outstanding problem. This project seeks to advance the fundamental interface science driving processes of dispersion and stabilization.	
Objectives	Study the contact dynamics during processing, such as contact angle hysteresis, may play a role in the static stability and should be investigated. Both long- and short-time factors should be considered. These factors may include gravitational settling/creaming, Oswald ripening, film drainage, etc. Produce a method to predict the static stability of particle stabilized (Pickering) emulsions and/or foams based on relating particle characteristics (size, shape, roughness, interparticle forces, etc.), solid loading, processing history, and liquid viscosity The project will use Simplified Industrial Formulations (SIFs) to investigate the emulsion stability, outline key factors influencing the stability and perhaps determine a predictive model.	
Scope	Particles are limited to SIFs. liquid(s) should be Newtonian. Solid loading between 1 and 50 vol% should be considered. The project should consider the emulsification/foaming method, but only the static stability should be considered.	

Recommended Contractors (2 or 3)

¹ Title used in meeting agendas and file archives ² One or more from the following list: W = wet systems; D = dry systems; F = particle formation; SR =size reduction; M = modeling; SE = systems engineering

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